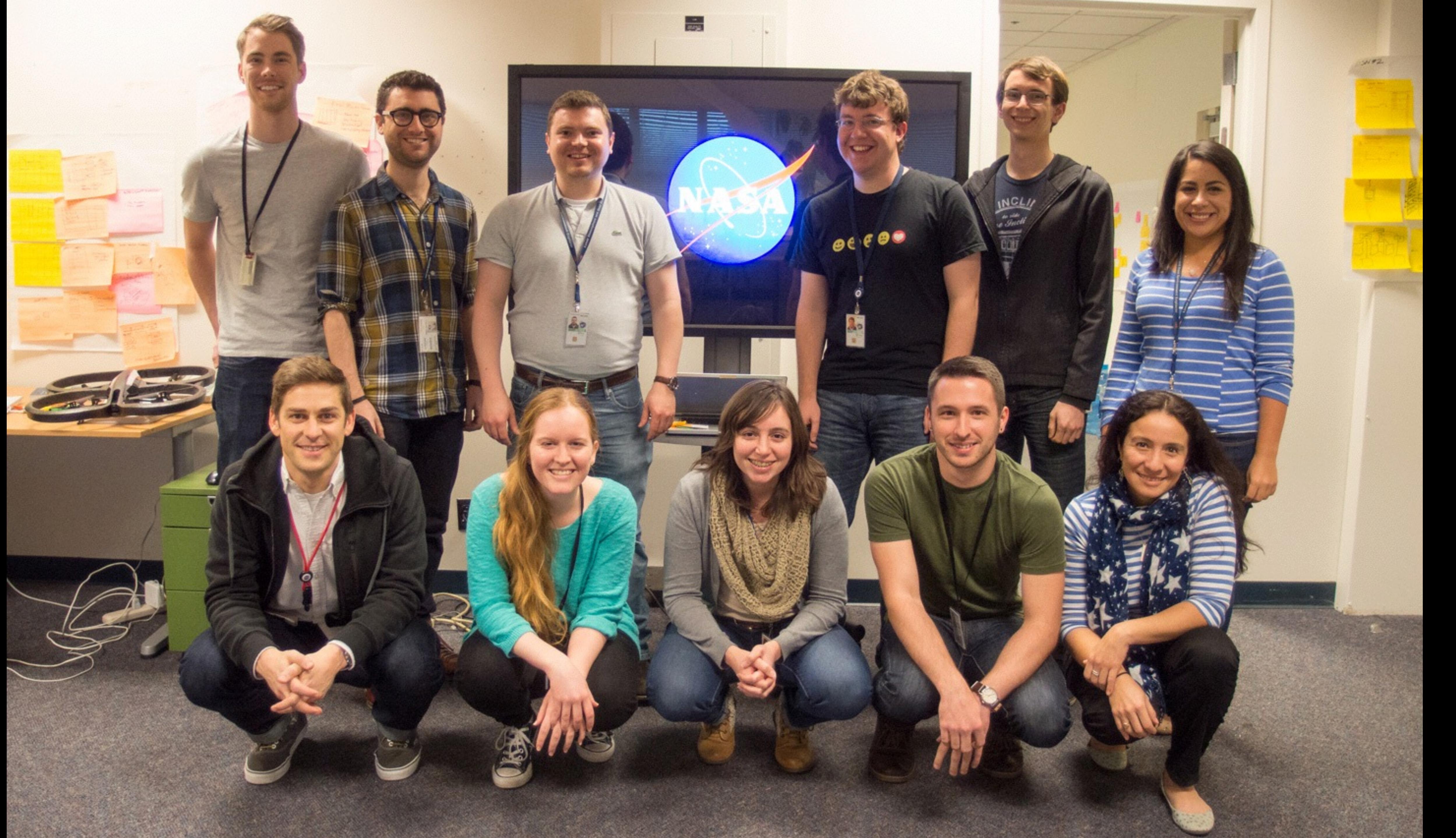


DESIGNING INTERFACES FOR ASTRONAUT AUTONOMY IN SPACE

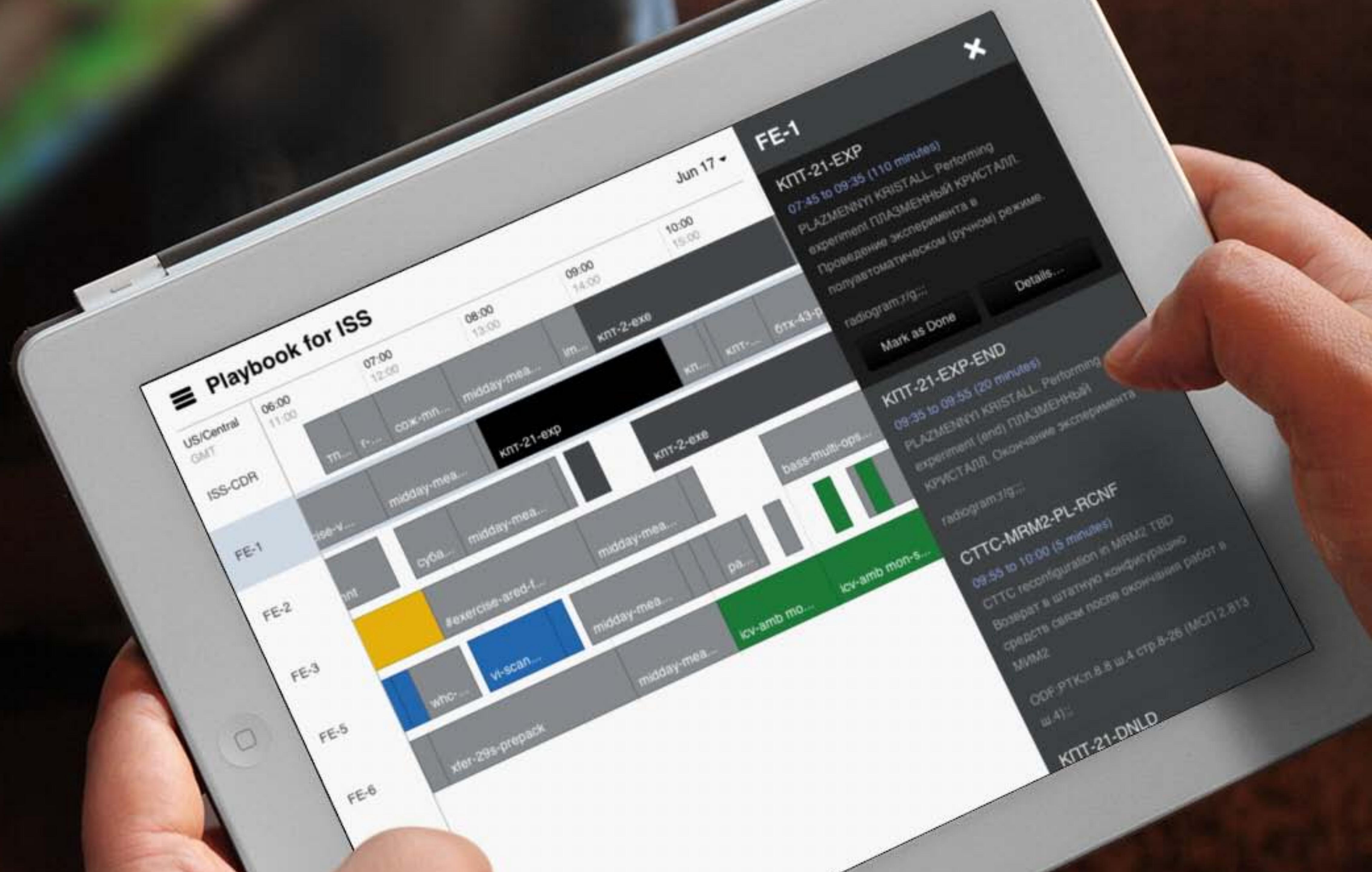
Steve Hillenius, NASA
@hillenius







(Star Trek Generations)





crew autonomy: allowing astronauts to make decisions on their own, with limited input from mission control



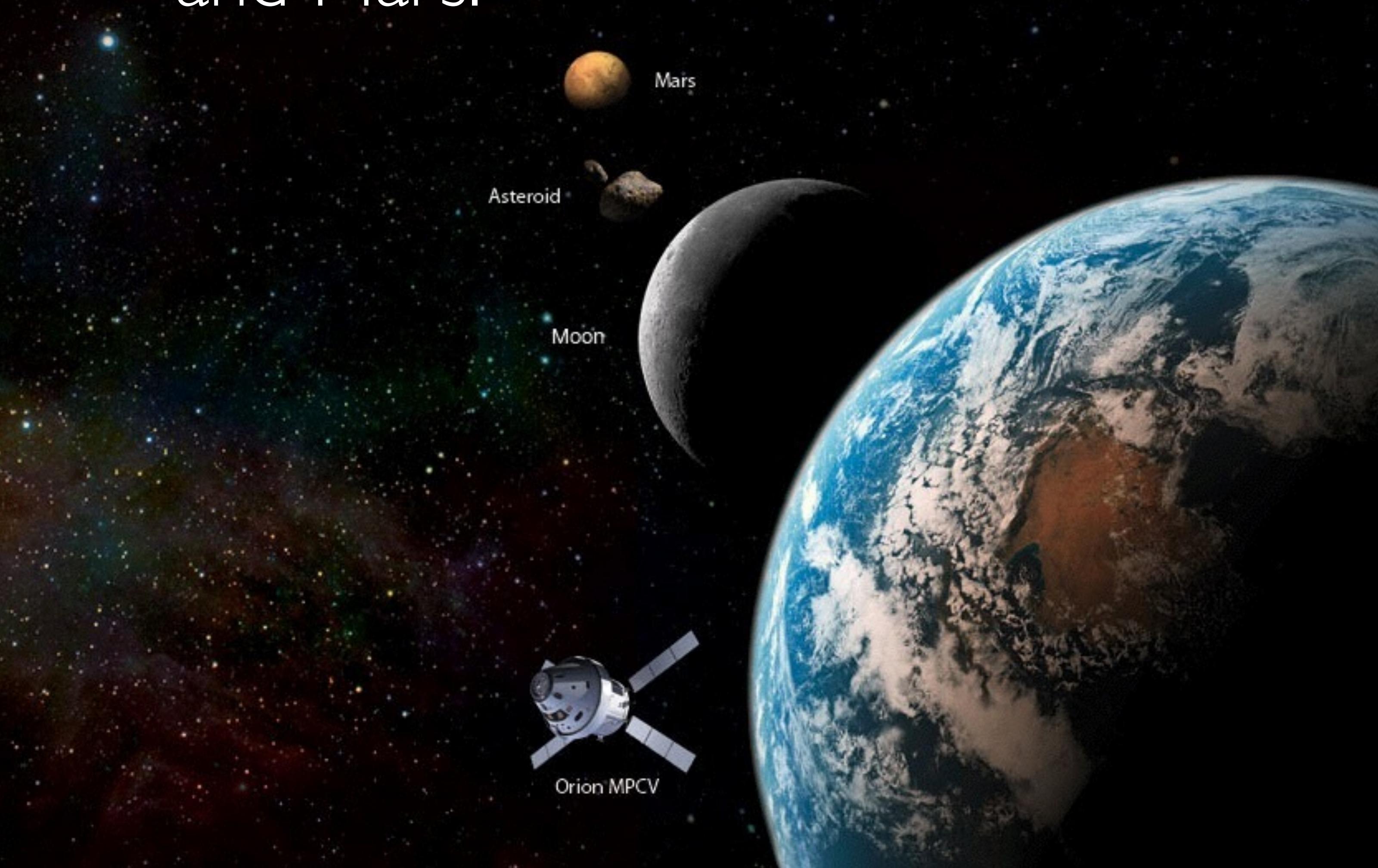
crew autonomy: allowing astronauts to make decisions on their own, without input from mission control

Why is it important?

- Astronauts want more autonomy
- Increased situational awareness
- Increased efficiency
- Future deep space missions



It can take anywhere from 8 to 48 minutes for roundtrip communication between Earth and Mars.









science experiments
maintenance
education/public outreach

mission planning
power planning
positioning and control
of the station
support for the crew

plus tons of other really **important** things!



6 astronauts



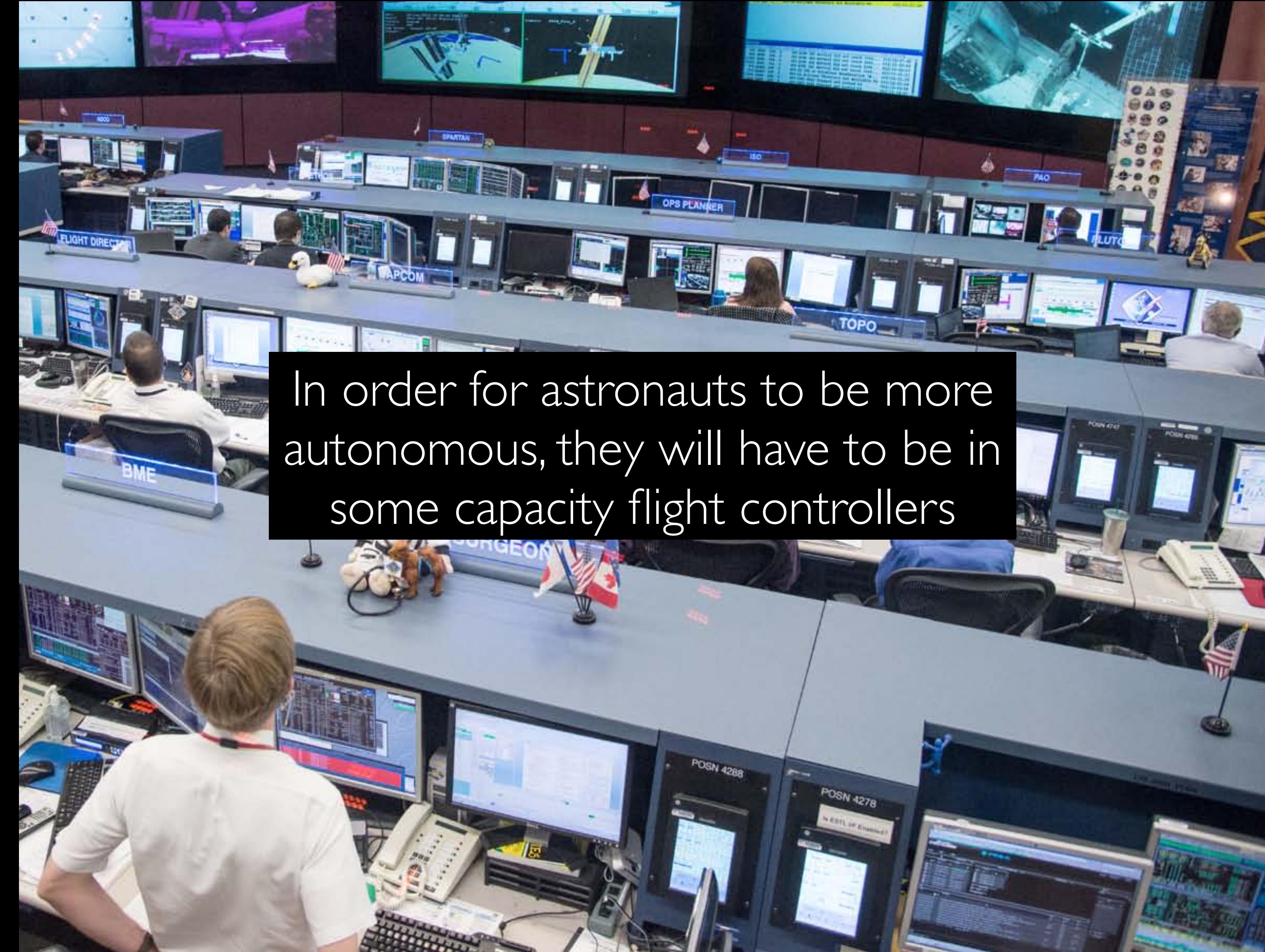
100s of flight controllers



6 astronauts



100s of flight controllers



In order for astronauts to be more autonomous, they will have to be in some capacity flight controllers

How do you design a tool that
allows astronauts to plan and
control their own missions?

*How do you design a tool that lets an
astronaut take on the roles of
hundreds of people?*

Design Constraints

Balance

Walk up and use

Mobile

Empowering

Efficient and Effortless

Advise, not enforce

Communication Time Delay Tolerant

11/08/07 16:36:39

OBJECTIVE:

Perform first stage capture following translation of U.S. Lab into ready-to-latch position for berthing to Node 1 Forward Active Common Berthing Mechanism (ACBM).

CBM capture latches are driven from initial position of 200° (fully deployed) to approximately 186°.

LOCATION:

Node 1/AFD EPSCS

DURATION:

5 minutes

REFERENCED PROCEDURE(S):

LAB INSTALL (FDF: PDRS OPS, NOMINAL LAB OPS)

NOTE

1. Step titles followed by the notation "(AOS/M)" indicate that AOS during the execution of that step is mandatory. If currently LOS or expecting LOS prior to completion of an AOS/M step, wait for the next AOS to perform step.
2. For any off-nominal steps or any attention symbols that appear, refer to [{NODE 1 CBM MATE MALFUNCTION}](#) (SODF: ASSY MAL: MALFUNCTION: CBM).
3. Step 1 is nominally performed with the SRMS in Position Hold mode.
4. Capture sequence may be initiated with three of four RTLs closed. In this case, the latch associated with the open RTL must be masked.

1. READY-TO-LATCH INDICATORS (RTLs) CLOSED VERIFICATION

✓Step 7 of LAB INSTALL complete (FDF: PDRS OPS, NOMINAL LAB OPS)

PCS [Node 1: S&M](#)
 [Node 1:S&M](#)

sel Forward CBM

[Node 1 Forward CBM Display](#)
'Functional CBM Representation (External View)'

✓RTL indications (four) – green

If RTL X (where X = 1, 2, 3, 4) is gray after repeated attempts to gain ready to latch indication

✓MCC for go

sel Latch X

[Capture Latch X Details](#)

sel Commands

[Latch_X_Cmds](#)

cmd Mask Latch X Execute

[Node 1 Forward CBM Display](#)

'Functional CBM Representation (External View)'

✓Latch X – Ø

2. FIRST STAGE CAPTURE PERFORMANCE (AOS/M)

CAUTION

To prevent damage to active CBM (ACBM), free drift (DAP: FREE for shuttle control or thruster inhibit for SM control) is required from initiation of CBM capture latch operation until a minimum of eight alternating bolts (every other bolt) have completed the ABolts command. SRMS shall remain grappled to U.S. Lab until such time.

A6U ✓DAP: FREE

PCS [Node 1 Forward CBM Display](#)
'Commands by Task'

sel Mate

[Node 1 Fwd CBM Mate](#)
'Capture Passive CBM'

cmd Capture First Stage Execute

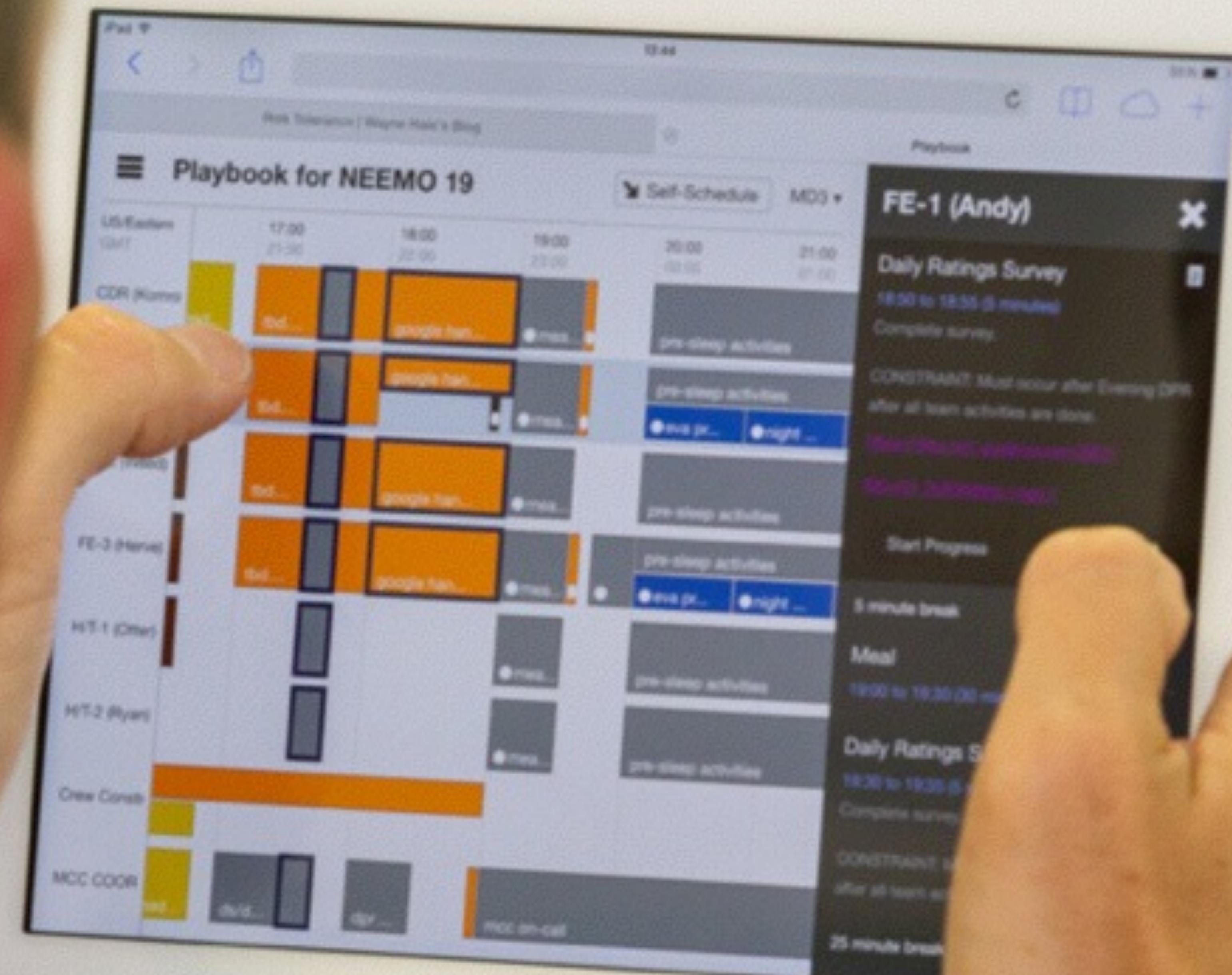
'Confirmation Request'

✓Override Capture Command?

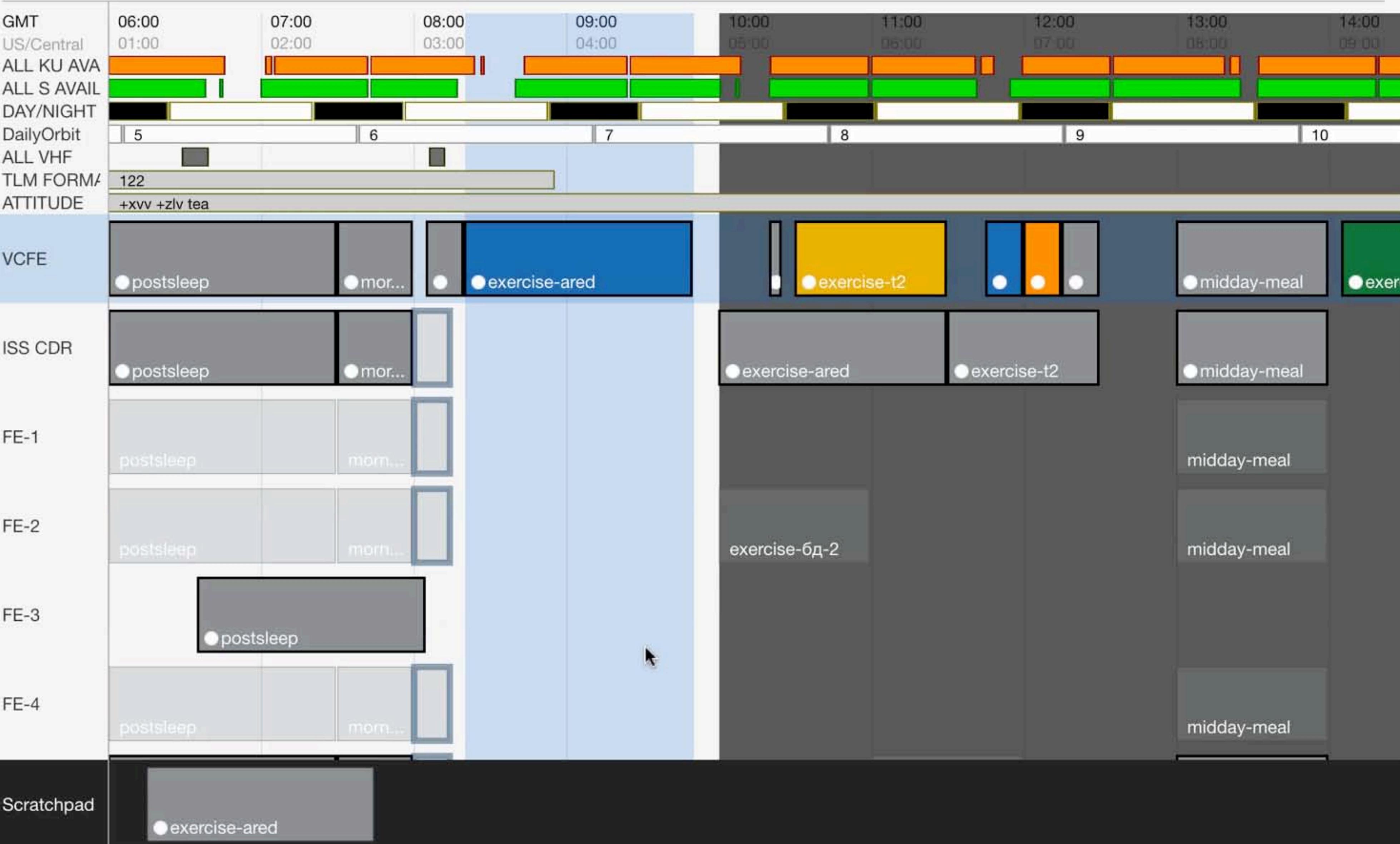
cmd Yes Execute

(Command requires approximately 15 seconds.)





Playbook for ISS

[Zoom In](#)
[Zoom Out](#)
[Self-Schedule](#)
[Sep 16](#)
VCFE

EXERCISE-ARED

08:20 to 09:50 (90 minutes)

US SODF; Med Ops - Medical Operations: 2.

Nominal: CMS; 2.1.175 ARED - Exercise; US

SODF; Med Ops - Medical Operations: 5.

Reference: CMS; 5.0.100 ARED - Exercise

Spreadsheet Reference:

Countermeasures System (CMS) Advanced

Resistive Exercise Device (ARED) Exercise

Session

Физические упражнения (ARED)

[Start Progress](#)
[Details...](#)

30-minute break (from 09:50 to 10:20)

P/TV-T2 VIDEO-S/U

10:20 to 10:25 (5 minutes)

Position the node 1 camcorder to provide a
side view of entire body with exercising
envelope and T2 in the rack for live downlink.

REF ONLY: US SODF; ISS PTV; SCENES;

PTV 120 T2 ACO Camcorder Setups; Step 3



I, E, G, T, S, R, A

≡ Playbook for ISS

Zoom In

Zoom Out

Self-Schedule

Sep 16 ▾



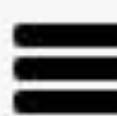






F10 Program





Playbook for NEEMO 19

[+ Add Note](#)

Copy MD7 17:07:41. We'll be waiting!!

[Add Photo, Video, or Files](#)[Add Note](#)

17:09:19
MD7



Potted up yesterday:

- Skin-B Kit
- HEADS-UP laptop
- MobiPV kit
- 3 complete GGlass (with chargers and earbuds)
- Surface Sampling Kit

The rest of the hardware is packed in Aquarius and will follow us in the potting up today.

⌚ 01:14 UNTIL DELIVERY • EARLIEST RESPONSE 17:19:19

17:07:41
MD7



Good morning NEEMO MCC! Or are we just speaking to an empty room because everyone is on call for a well deserved morning off? All is well and everyone is well at 7ft and ascending!

DELIVERED • EARLIEST RESPONSE 17:17:41

Playbook for NEEMO 20 Crew

Self-Schedule

MD11

Scratchpad



Install CORAL II Panels

(10 minutes)

CORAL II Tower panel (3x) installation

Must be completed after CORAL II Tower assembly.

Start Progress

Details...

Cameras install CORAL I

(15 minutes)

Camera installation on CORAL I Tower

Must be completed after CORAL I Panel Removal.

Site Survey

(35 minutes)

Translate to site (5min)

Pre-Sample Survey & Take PAM





DESIGNING INTERFACES FOR ASTRONAUT AUTONOMY IN SPACE

Steve Hillenius, NASA
@hillenius

